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Modelling and Simulation of Vehicle to Vehicle Communication

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Abstract: With the rapid advancement in communication technologies, Intelligent Transportation System (ITS) has also gained its significance, aiming to improve efficiency and safety of transportation activities. Vehicle to Vehicle (V2V) and Vehicle to Infrastructure (V2I) are the main contributors of ITS architecture. The term used for communication among the vehicles is referred as Vehicular Ad-Hoc network (VANET), VANET is special kind of Mobile Ad-hoc Network (MANET), rapid change in mobile nodes (car/vehicles) in case of VANET makes it different from MANET, while sharing all other features of MANET. VANET has many advantages including minimising traffic, reducing car accidents, co-operative awareness, environmental safety by monitoring CO₂ emission. For developing protocols and algorithms to achieve above stated features out of VANET/ITS one need to test them through simulation, there are lots of Network simulators available which can simulate ad-hoc network but again coming to the complex part of VANET it has dense nodes with high mobility in VANET, obviously it is not possible through network simulators to simulate city traffic where each vehicle is considered as node, so a need to model the city scenario into nodes and edges structure evolves which can be further fed to network simulators to test algorithms efficiency and protocols correctness, in proposed work we will be modelling the scenario of Clock Tower, Dehradun city, the route contains two lane roads and other link roads along with buildings and parks. Modelling will be done using SUMO and Open StreetMap will be converted to SUMO networks and finally simulations will be done using VEINS through OMNET++.

Keywords: VANET, SUMO, OMNeT++, VEINS, ITS, OpenStreetMaps, VANET Modelling, VANET Simulation.

1. INTRODUCTION

Simulation is needed where physical implementation is not feasible to test some rough concepts, among many road traffic and safety is one of the major problem concern of this modern world.

Critical traffic problems such as accidents and traffic congestion require the development of new transportation systems [1]. The need for some mechanism comes where one can model the real traffic in simulation and then dive in to propose solutions to the problems like traffic congestion, alternate route finding, minimising red light stoppage, Co₂ emission by controlling the flow of vehicles and many more. Post modelling

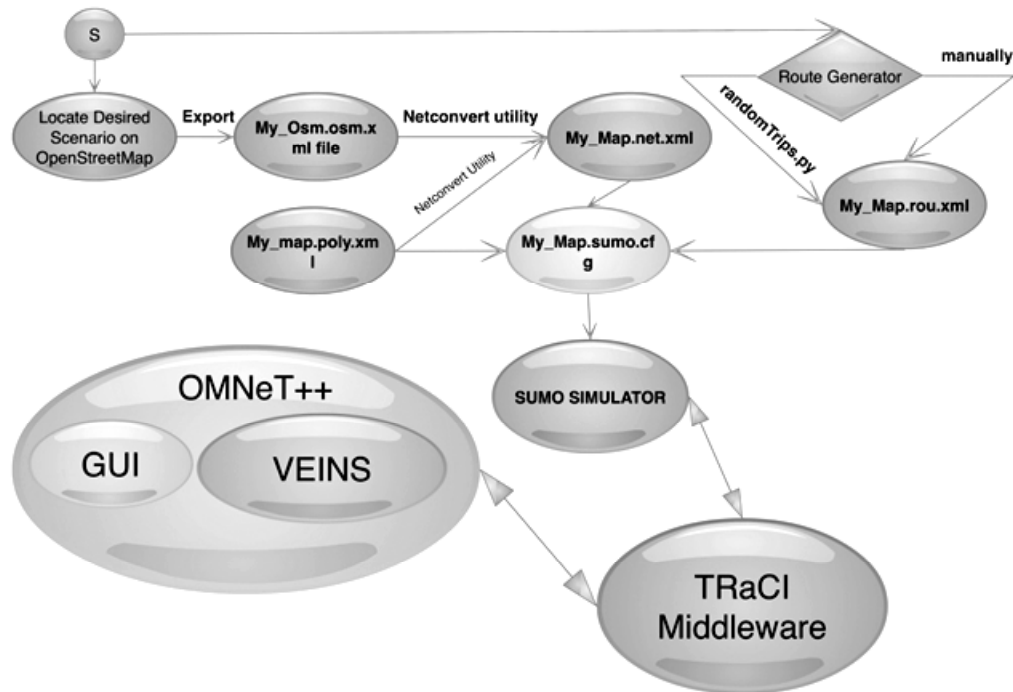


Figure 1: Process flow for entire simulation

it is needed to make those simulated vehicles intelligent so to make decisions and establish communication among each other for coming to some decision. VANET has a major challenge of Vehicles come and lose contact in a matter of seconds as speed is measured in miles per hour. [2] Here comes network simulators in picture which considers these vehicles as nodes and enables them to communicate with each other for real time decision making and behaving. During simulation data is processed and an overall decision is been taken for platoons of vehicles through which they behave. To start with modelling we need to have some geographic location such as city or some specific area, which will be our area where we want dodo some simulation. for this purpose we will be taking maps from OpenStreetMap[3][4], these maps will be then fed into SUMO[5] for modelling and then VEINS[8] framework will be used to make a realistic Vehicular Simulation using mobility from SUMO and Network from OMNeT++[7]. Any VANET application which needs simulation will obviously have to pass through all above mentioned phases. However there are different tools and techniques available to attain the goal each having its own merit and demerits . We present the mostly used and reliable method which also simulates as realistic as possible, without sacrificing speed and resources. The flow of entire process is shown in Figure 1. This paper is classified into 7 Sections, Section 2 elaborates OpenStreetMap and importing of maps from OpenStreetMaps, Section 3 explains about SUMO and modelling the map, Section 4 is dedicated to the OMNeT++ Simulator and Section 5 explains how VEINS framework is a comprehensive suite for SUMO and OMNeT++. Section 6 discuss the simulation parameters and results and finally Section 7 concludes the entire work done.

2. OPENSTREETMAP

OpenStreetMap (OSM) is a collaborative project by community and group of researchers to create a free editable map of the world.

OpenStreetMap®[3] is *open data*, licensed under the Open Data Commons Open Database License (ODbL) by the OpenStreetMap Foundation (OSMF). User can simply visit the openstreet website[2] and export the specific geographic location, downloaded file would be a *.osm.xml file which is accepted by mostly all the

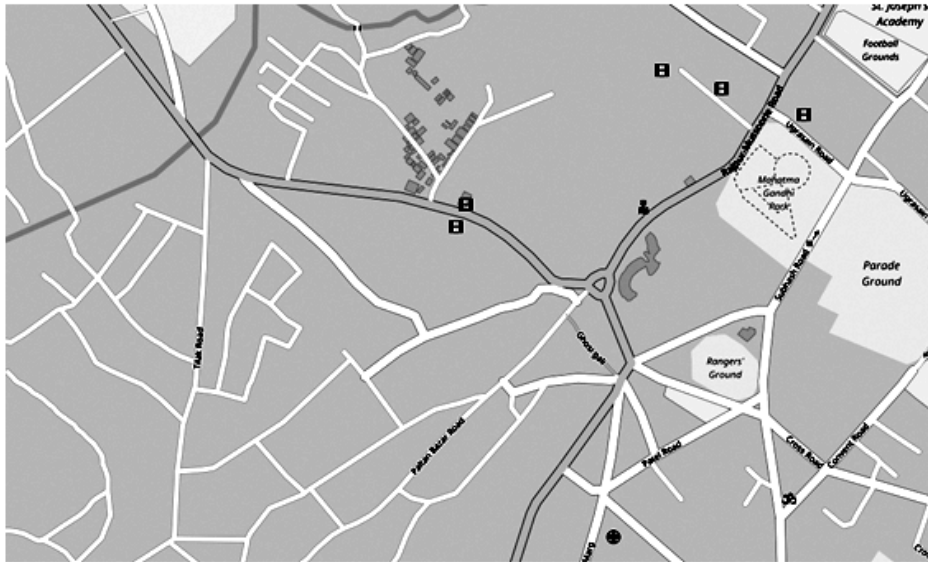


Figure 2: Map of Dehradun City

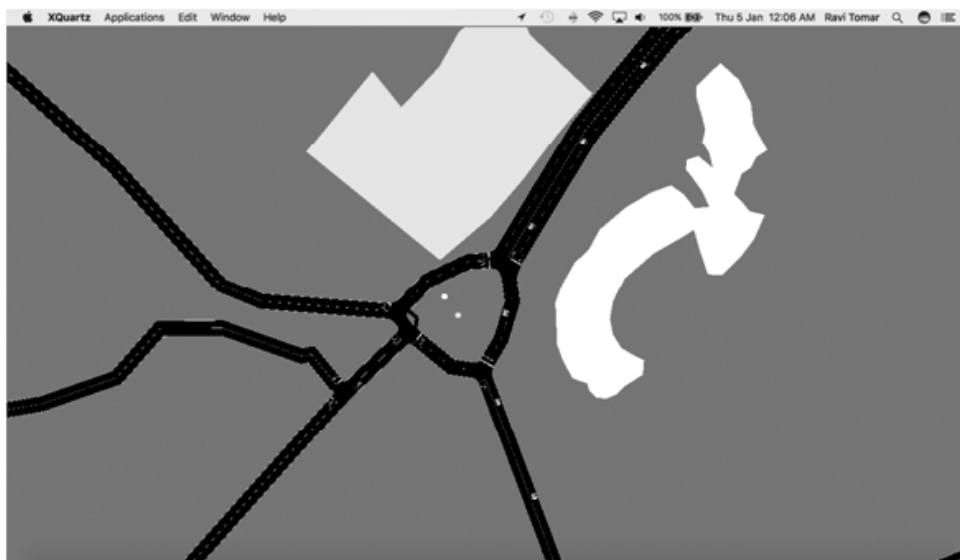


Figure 3: SUMO Simulation Model

simulators available. The downloaded osm file needs to be converted into *.net.xml file to be used by SUMO simulator. There are two ways of doing this the simpler one is the three clicks scenario generation. Python script is available inside tools folder of SUMO package, describe simply helps in downloading the map from open Street map and converting to SUMO supported format very comfortably and easily. Syntax for this method is :

```
python<SUMO_HOME>/tools/osmWebWizard.py
```

Figure 2 shows the selected area to be downloaded. The other method is using a utility named netconvert which is provided along with the sumo bundle. The net convert utility is used to convert the osm.xml file to the network file *.net.xml of SUMO. Syntax is given below :

```
netconvert —osm mymap.osm.xml -o mymap.net.xml.
```

The first method is easier to generate the first model but to generate custom models we need to do the manual method that is hundred convert which also takes different inputs during its execution like buildings hurdles left-hand drive etc. Further information can be seen in [4].

3. SUMO – SIMULATION OF URBAN MOBILITY

SUMO is a free and open traffic simulation suite which is available since 2001 and is used to model traffic scenario's SUMO[4] provides GUI interface which can be started by typing sumo-gui at terminal once installation is done and path is set. SUMO comes with lots of tools available for achieving modelling rapidly, one such example is discussed in importing Open Street Maps, Other example is to create random traffic on road network which can be generated through randomTrips.py script available along with sumo bundle. SUMO creates a network by converting all roads to be the edges(*.edg.xml file) and all vehicles to be the nodes, as VANET is mobile network so all nodes moves along with the edges, and this movement is defined in route file(*.rou.xml), route file may contain individual path for all nodes or a flow can be created for platooning vehicles on same path at regular intervals. apart from this sumo also facilitates by providing a polygon file (*.poly.xml) which is basically the buildings and parks etc in real world along the edges. These three files acts as mandatory input to the SUMO simulator which are mentioned in a configuration file (*.sumo.cfg), this configuration file along with all three supporting files are given as input to sumo-guisimulator. We have created a model of city along with traffic by now , we can see the running nodes in Figure 3, yellow cars are nodes and black strips are road while rest polygons are buildings.

4. OMNET++

OMNeT++ is an open-source object-oriented modular discrete event network simulation framework. It has a generic architecture [7]. It is used to model computer networks or just as well for queueing network simulations. OMNeT++

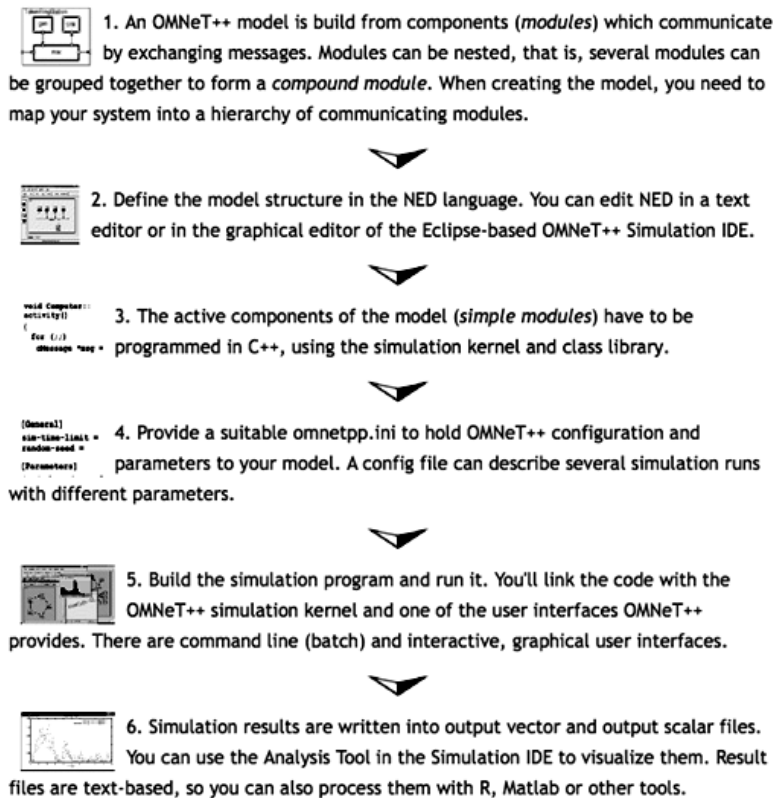


Figure 4: Working Sequence for OMNET++ Simulation[10]

provides only the necessary framework for developing a certain simulation module, and these models are developed independently in OMNeT++, they follow their own release cycles. This means that several frameworks can be modelled in the same research area [8]. OMNeT++ itself is not a concrete simulator but it is totally a building block kind of framework, it comprises of C++ library consisting Simulation kernel and some basic utility classes such as random number generator, topology discovery etc. It just provides an infrastructure to create simulations and these configurations are done in *.ned files. Figure 4 shows the abstract working scenario of any OMNeT++ Simulation. We start with collecting the modules available which will be used for our scenario and all modules will communicate through message exchange among themselves. Then a NED file is created which models the hierarchy and structure of all modules, all the active modules need to be coded in C++ so the working logic can be implemented there and finally define omnetpp.ini file which is the final point of passing values to the simulation. All these are compiled and linked to the OMNeT Simulator kernel which gives us the simulation based on our scenario generation, as output finally OMNeT creates two kind of files output vector and output scalar files. These files can be used to analyse and validate the process using any available tool like R, visualisation tool is also provided in the OMNeT IDE.

5. VEINS (VEHICLES IN NETWORK SIMULATION)

Veins is an open source framework for running vehicular network simulations. It is based on two well-established simulators: OMNeT++, an event-based network simulator, and SUMO, a road traffic simulator [11]. Models generated in Veins are executed by an event-based network simulator (OMNeT++) while interacting with a road traffic simulator (SUMO). Other components of Veins take care of setting up, running, and monitoring the simulation. Veins provide a all at one place suit of IVC-specific modules, Figure 5 shows the VEINS framework, we can see all modules are running under OMNeT++ Kernel and simulation control is maintained by OMNeT++ while Mobility is provided by SUMO through TRaCIServer. VEINS comes with many modules and are used as per our requirement, it also contains various obstacles modules which depicts real world building interference during simulation. VEINS finally gives us output in 2 files of OMNET which are text based scalar and vector output, which can be further analysed to get results.

6. SIMULATION

Now, we have understood all the tools and framework used to model and simulate any scenario, here we have done the simulations through VEINS framework on OMNET++ which is connected to SUMO via local client

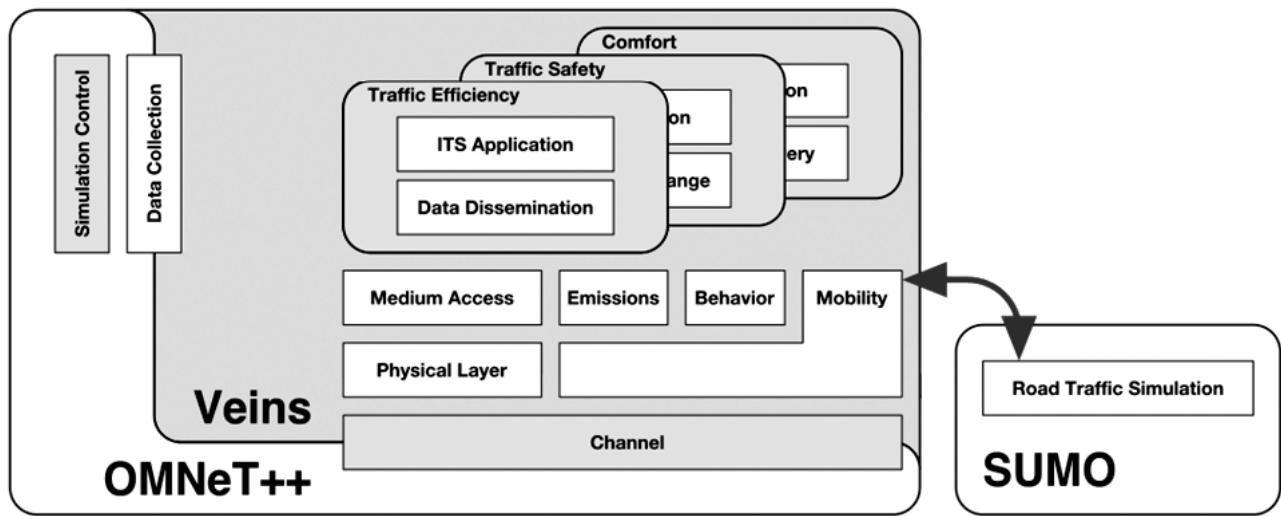


Figure 5: VEINS Framework

```

veins-veins-4.4 — python sumo-launchd.py -vv -c sumo-gui — 80x24
Last login: Thu Jan  5 00:03:19 on ttys000
[Ravis-MBP:~ ravitomar$ cd Simulations/veins-veins-4.4
[Ravis-MBP:veins-veins-4.4 ravitomar$ python
.DS_Store      .oppfeatures  README.MiXiM.txt  examples/
.cproject      .project      README.txt        images/
.gitignore     CHANGELOG     configure         src/
.nedfolders    COPYING       doc/              sumo-launchd.py
.oppbuildspec Makefile      doxy.cfg         tests/
[Ravis-MBP:veins-veins-4.4 ravitomar$ python sumo-launchd.py -vv -c sumo-gui
Logging to /var/folders/jf/cf6g1jm57d3fkxqc7cl0sb3r0000gn/T/sumo-launchd.log
Listening on port 9999

```

Figure 6: VEINS TRaCI middleware script running

server model, and to establish this we take help of TraCI(Traffic Control Interface) which is distributed along with SUMO bundle in src folder.[8] TraCI works as middleware to connect SUMO and OMNET++.VEINS framework which is running inside

OMNET++ provide a python script named *sumo-launchd.py*, this script creates a client-server connection between SUMO TraCI server connection and VEINS via OMNET++, Figure 6 shows the sever waiting on terminal listening on port 9999 at localhost. When simulation starts on OMNET++ it sends a request to TRaCI server and gets nodes location in response, thereby creating a realtime road network on OMNET++ Simulation panel.This step is to share SUMO mobility on OMNET++, now comes the role of Network Simulator OMNET++

Table 1: Simulation Parameters

debug-on-errors
print-undisposed
sim-time-limit
** .scalar-recording
** .vector-recording
** .debug
** .coreDebug
* .playgroundSizeX
* .playgroundSizeY
* .playgroundSizeZ

Table 2: WaveApp Layer Parameters

true	*.node[*].applType	“TraCIDemo11p”
false	*.node[*].appl.debug	false
6000s	*.node[*].appl.headerLength	256 bit
true	*.node[*].appl.sendBeacons	false
true	*.node[*].appl.dataOnSch	false
false	*.node[*].appl.sendData	true
false	*.node[*].appl.beaconInterval	1s
25000m	*.node[*].appl.beaconPriority	3
25000m	*.node[*].appl.dataPriority	2
50m	*.node[*].appl.maxOffset	0.005s

Table 3
11p specific parameter

*.connectionManager.pMax	20mW
*.connectionManager.sat	-89dBm
*.connectionManager.alpha	2.0
*.connectionManager.carrierFrequency	5.890e9 Hz
*.connectionManager.sendDirect	true

(contd...Table 3)

*.**.nic.mac1609_4.useServiceChannel	false
*.**.nic.mac1609_4.txPower	20mW
*.**.nic.mac1609_4.bitrate	18Mbps
*.**.nic.phy80211p.sensitivity	-89dBm
*.**.nic.phy80211p.useThermalNoise	true
*.**.nic.phy80211p.thermalNoise	-110dBm
*.**.nic.phy80211p.decider	xmlDoc("config.xml")
*.**.nic.phy80211p.analogueModels	xmlDoc("config.xml")
*.**.nic.phy80211p.usePropagationDelay	true

Table 4: TraCIScenarioManager parameters

Table 5: Mobility Parameters

*.manager.updateInterval	0.1s	*.node[*].veinsmobilityType	"org.car2x.veins.modules.mobility.traci.TraCIMobility"
*.manager.host	"localhost"	*.node[*].mobilityType	"TraCIMobility"
*.manager.port	9999	*.node[*].mobilityType.debug	true
*.manager.moduleType	"org.car2x.veins.nodes.Car"	*.node[*].veinsmobilityType.debug	true
*.manager.moduleName	"node"	*.node[*0].veinsmobility.accidentCount	1
*.manager.margin	25	*.node[*0].veinsmobility.accidentStart	75s
*.manager.launchConfig	xmlDoc("erlangen.launchd.xml")	*.node[*0].veinsmobility.accidentDuration	30s

which implies communication between the nodes and make vehicles exchange data. Using Veins framework in OMNET++ we simulate our scenario and Table 1-5 shows various parameters specified in omnetpp.ini file which is required by OMNeT simulator to run simulations. Table 1 shows scenario specific parameters such as playground size which is taken as 25000m by 25000m and simulation time is set to 6000s. Table 2 shows the configuration parameters for WaveAppLayer used for communication between nodes/vehicles, here applType represents the protocol used for information exchange.

Table 3 shows 802.11p specific parameters for Network Interface cards like Transmission Power, carrier frequency, bitRate etc. Table 4 shows TraCI specific settings, here we can see that we are sending our request to localhost and on port number 9999 where SUMO TraCI server is already started and Table 5 shows Mobility parameters, from here we can configure number of accidents which can happen to any node, at what time accident is scheduled and by when accident will be resolved. All this is taken care by OMNET++ and VEINS together and finally Figure 8 shows complete simulation and automatic rerouting of vehicles on sensing a accident.

7. CONCLUSION

This paper demonstrated the modelling and simulation of real world scenario/traffic and scheduled an accident, which acts as an event generator for all following vehicles, vehicles receiving signals again rebroadcasts the event information to other vehicles in vicinity. The algorithm automatically changes the route of following vehicles once accident is detected and threshold time is lapsed. Figure 7 shows Node 110-Node 116 are been rerouted towards destination when Node 50 is unable to recover from accident for so long.

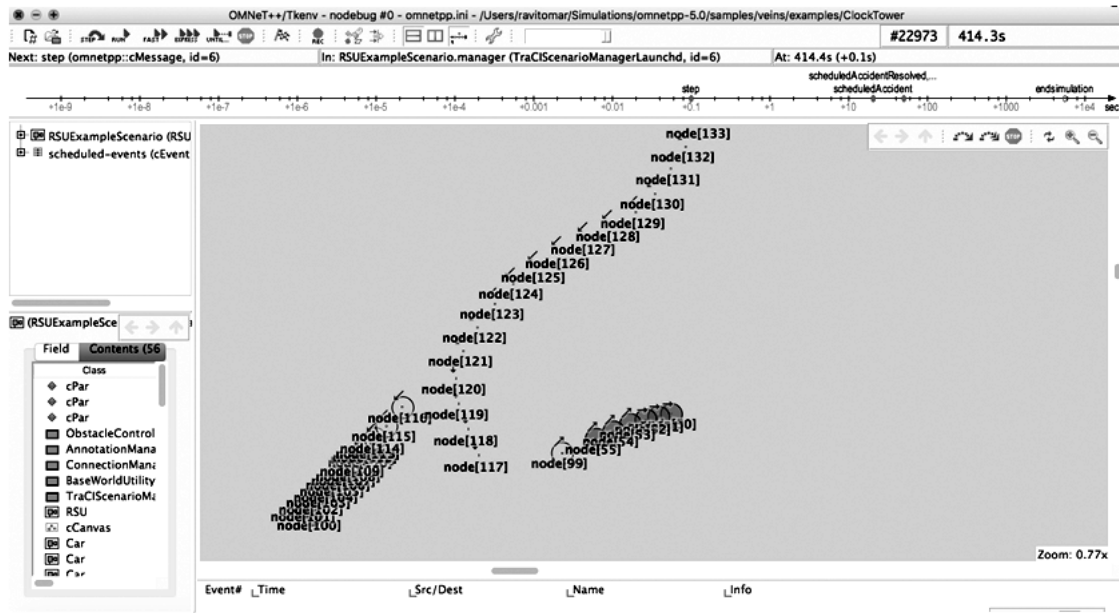


Figure 7: Simulation of Vehicles on OMNET++(RED one waited for more than 10sec)
(Left One are re-routed because of accident)

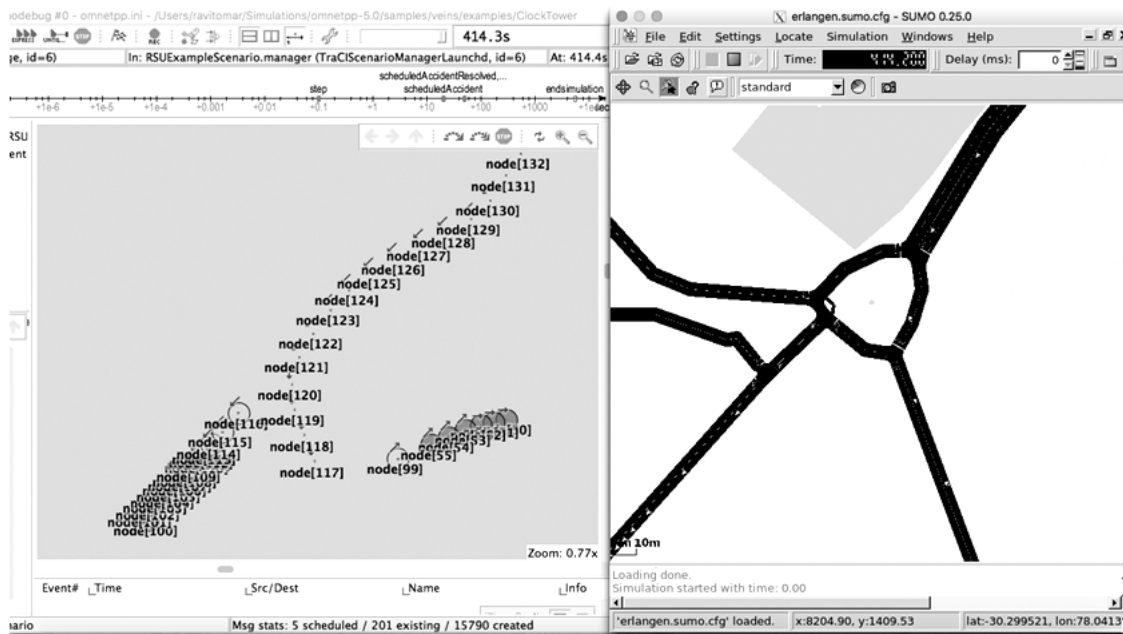


Figure 8: OMNET++ and SUMO hand in hand via TRaCI

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