# GLOBAL ATTRACTIVITY OF A RATIONAL RECURSIVE SEQUENCE 

Wan-Sheng He, Lin-Xia Hu \& Wan-Tong Li


#### Abstract

In this paper we investigate the boundedness, the periodic character and global attractivity of the recursive sequence $$
x_{n+1}=\frac{a+b x_{n-k}}{A-x_{n}}, n=0,1, \ldots,
$$ where $a \geqslant 0, b, A>0$ are real numbers, $\mathrm{k} \in\{1,2, \ldots\}$ and the initial conditions $x-k, \ldots, x_{0}$ are arbitrary real numbers. We show that the positive equilibrium of the equation is a global attractor with a basin that depends on certain conditions posed on the coefficients.


## 1. INTRODUCTION

Our goal in this paper is to investigate the boundedness, the periodic character and global attractivity of all positive solutions of the recursive sequence

$$
\begin{equation*}
x_{n+1}=\frac{a+b x_{n-k}}{A-x_{n}}, n=0,1, \ldots \tag{1.1}
\end{equation*}
$$

where $a \geqslant 0, b, A>0$ are real numbers, $\mathrm{k} \in\{1,2, \ldots\}$ and the initial conditions $x_{-}$ ${ }_{k}, \ldots, x_{0}$ are arbitrary real numbers.

In [12], Li and Sun investigated the global asymptotic stability of the rational recursive sequence

$$
x_{n+1}=\frac{a-b x_{n-k}}{A-x_{n}}, n=0,1, \ldots
$$

[^0]Key word: Difference equation, boundedness, global attractivity, periodic character.
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where $a, b, A$ are nonnegative real numbers and $k \in\{1,2, \ldots\}$. In [6], He et al. investigated the global asymptotic stability of the rational recursive sequences

$$
x_{n+1}=\frac{a-b x_{n-1}}{A+x_{n}}, n=0,1, \ldots,
$$

where $a \geqslant 0, A, b>0$ are real numbers, and the initial conditions $x_{-1}, x_{0}$ are arbitrary positive real numbers. For the global behavior of solutions of some related equations, see $[1,2,3,14]$. Other related results refer to $[4,5,7,8,9,10,11,13,15,16]$.

Here, we recall some results which will be useful in the sequel.
Let $I$ be some interval of real numbers and let $F$ be continuous function defined on $I^{k+1}$. Then, for initial conditions $x_{-k}, \ldots, x_{0} \in I$, it is easy to see that the difference equation

$$
\begin{equation*}
x_{n+1}=F\left(x_{n}, \ldots, x_{n-k}\right), n=0,1, \ldots \tag{1.2}
\end{equation*}
$$

has a unique solution $\left\{x_{n}\right\}_{n=-k}^{\infty}$.
A point $\bar{x}$ is called an equilibrium of Eq. (1.2), when $\bar{x}=F(\bar{x}, \ldots, \bar{x})$, that is, $x_{n}=\bar{x}$ for $n \geq 0$, is a solution of Eq.(1.2), or equivalently, is fixed point of $F$.

The linearized equation with Eq.(1.2) about an equilibrium $\bar{x}$ is

$$
y_{n+1}=\sum_{i=0}^{k} \frac{\partial F}{\partial x_{i}}(\bar{x}, \ldots, \bar{x}) y_{n-i}, n=0,1, \ldots,
$$

and its characteristic equation is

$$
\lambda^{n+1}=\sum_{i=0}^{k} \frac{\partial F}{\partial x_{i}}(\bar{x}, \ldots, \bar{x}) \lambda^{n-i}, n=0,1, \ldots .
$$

Definition 1.1. An interval $J \subset I$ is called an invariant interval of Eq.(1.2), if $x_{-k}, \ldots, x_{0} \in J \Rightarrow x_{n} \in J$ for all $n \geq 0$. That is, every solution of Eq.(1.2) with initial conditions in $J$ remains in $J$.

Theorem 1.1 Assume that $F$ is a $C^{1}$ function and let $\bar{x}$ be the equilibrium of Eq.(1.2). Then the following statements are ture.
(a) If all the roots of the polynomial equation

$$
\begin{equation*}
\lambda^{k+1}-\sum_{i=0}^{k} \frac{\partial F}{\partial x_{i}}(\bar{x}, \cdots, \bar{x}) \lambda^{k-i}=0 \tag{1.3}
\end{equation*}
$$

lie in the open unit disk $|\lambda|<1$, then the equilibrium $\bar{x}$ of Eq.(1.2) is locally asymptotically stable.
(b) If at least one of the roots of Eq.(1.3) has absolute value greater than one, then the equilibrium $\bar{x}$ of Eq.(1.2) is unstable.

Also, we need the following well-known explicit condition for local asymptotic stability.

Theorem1.2. Assume that $p_{1}, p_{2}, \ldots, p_{k} \in R$. Then $\sum_{i=1}^{k}\left|p_{i}\right|<1$ is a sufficient condition for the asymptotic stability of the difference equation

$$
x_{n+k}+p_{1} x_{n+k-1}+\ldots+p_{k} x_{n}=0, n=0,1, \ldots
$$

Theorem 1.3. Consider the difference equation

$$
x_{n+1}=F\left(x_{n}, \ldots, x_{n-k}\right), n=0,1, \ldots,
$$

where $k \in\{1,2, \ldots\}, F \in C\left[(0, \infty)^{k+1},(0, \infty)\right]$ is increasing in each of its arguments and the initial condition $x_{-k}, \ldots, x_{0}$ are positive. Assume that Eq.(1.2) has a unique positive equilibrium $\bar{x}$ and that the function $h$ difined by $h(x)=F(x, \ldots, x), x \in$ $(0, \infty)$ satisfies $(h(x)-x)(x-\bar{x})<0$ for $x \neq \bar{x}$. Then $\bar{x}$ is a global attractor of all positive solution of Eq. (1.2).

## 2. ASYMPTOTIC STABILITY

Consider the difference equation (1.1) with

$$
\begin{equation*}
a>0 \text { and } A>b>0 . \tag{2.1}
\end{equation*}
$$

The equilibria of Eq.(1.1) are the nonnegative solution of the quadratic equation

$$
\bar{x}^{2}-(A-b) \bar{x}+a=0
$$

and the linearized equation of Eq.(1.1) about $\bar{x}$ is

$$
y_{n+1}-\frac{\bar{x}}{A-\bar{x}} y_{n}-\frac{b}{A-\bar{x}} y_{n-k}=0, n=0,1, \cdots .
$$

Its characteristic equation

$$
\begin{equation*}
\lambda^{k+1}-\frac{\bar{x}}{A-\bar{x}} \lambda^{k}-\frac{b}{A-\bar{x}}=0 . \tag{2.2}
\end{equation*}
$$

According to our assumption, we have
if (2.1) holds and $a=(A-b)^{2} / 4$, then Eq.(1.1) has a unique positive equilibrium $\bar{x}_{0}=(A-b) / 2 ;$
if (2.1) holds and $a<(A-b)^{2} / 4$, then Eq.(1.1) has two positive equilibria

$$
\bar{x}_{1}=\frac{A-b+\sqrt{(A-b)^{2}-4 a}}{2} \text { and } \bar{x}_{2}=\frac{A-b-\sqrt{(A-b)^{2}-4 a}}{2}
$$

Thus, we obtain the following results.
Theorem 2.1. Assume (2.1) holds. Then
(a) the positive equilibrium $\bar{x}_{2}$ of Eq.(1.1) is locally asymptotically stable (In the sequel, we will denote $\bar{x}_{2}$ as $\bar{x}$ ).
(b) the positive equilibria $\bar{x}_{0}$ and $\bar{x}_{1}$ of Eq.(1.1) are unstable.

Proof. (a) By (2.2), the characteristic equation (2.2) about $\bar{x}_{2}$ is

$$
\lambda^{k+1}-\frac{A-b-\sqrt{(A-b)^{2}-4 a}}{A+b+\sqrt{(A-b)^{2}-4 a}} \lambda^{k}-\frac{2 b}{A+b+\sqrt{(A-b)^{2}-4 a}}=0 .
$$

By Theorem 1.2, we have

$$
\begin{aligned}
& \left|-\frac{A-b-\sqrt{(A-b)^{2}-4 a}}{A+b+\sqrt{(A-b)^{2}-4 a}}\right|+\left|\frac{2 b}{A+b+\sqrt{(A-b)^{2}-4 a}}\right| \\
= & \left|\frac{A+b-\sqrt{(A-b)^{2}-4 a}}{A+b+\sqrt{(A-b)^{2}-4 a}}\right|<1 .
\end{aligned}
$$

Hence, the positive equilibrium $\bar{x}_{2}$ is locally asymptotically stable.
(b) Similarly, the positive equilibria $\bar{x}_{0}$ and $\bar{x}_{1}$ of Eq. (1.1) are unstable for $k \in$ $\{1,2, \ldots\}$.

## 3. GLOBAL ATTRACTIVITY

In this section, we study the global attractivity of all positive solution of Eq.(1.1). We show that the positive equilibrium $\bar{x}$ of Eq.(1.1) is a global attractor with a basin that depends on certain conditions posed on the coefficients.

Lemma 3.1. Assume (2.1) holds. Then the following statements are true.
(a) $0<\bar{x}<\bar{x}_{1}<A$.
(b) Let $F\left(x_{n}, \ldots, x_{n-k}\right)=\frac{a+b x_{n-k}}{A-x_{n}}$, so $F$ is a strictly increasing function in $\left(-\infty, \bar{x}_{1}\right)$.

Proof. The proof of (b) is obviously and will be omitted. We only prove (a). In view of

$$
A-\bar{x}_{1}=A-\frac{A-b+\sqrt{(A-b)^{2}-4 a}}{2}=\frac{A+b-\sqrt{(A-b)^{2}-4 a}}{2}>0 .
$$

and the definitions of $\bar{x}$ and $\bar{x}_{1}$, the proof is obvious and complete.
Lemma 3.2. Suppose that the function $h$ defined by

$$
h(x)=F(x, \cdots, x)=\frac{a+b x}{A-x}, x \in\left(0, \bar{x}_{1}\right) .
$$

Then $(h(x)-x)(x-\bar{x})<0$ for $x \neq \bar{x}$.
Proof. By the definition of $h$, we have

$$
\begin{aligned}
& (h(x)-x)(x-\bar{x}) \\
= & \left(\frac{a+b x}{A-x}-x\right)(x-\bar{x})=\frac{1}{A-x}\left(x^{2}-(A-b) x+a\right)(x-\bar{x}) \\
= & \frac{1}{A-x}\left(x-\frac{(A-b)+\sqrt{(A-b)^{2}-4 a}}{2}\right)\left(x-\frac{(A-b)-\sqrt{(A-b)^{2}-4 a}}{2}\right)(x-\bar{x}) \\
= & \frac{1}{A-x}\left(x-\bar{x}_{1}\right)(x-\bar{x})^{2}<0 \text { for } x \neq \bar{x} .
\end{aligned}
$$

The proof is complete.
Theorem 3.1. Assume that $0<a<(A-b)^{2} / 4$ and $A>b>0$ hold. Let $\left\{x_{n}\right\}$ be a solution of Eq.(1.1). If $\left(x_{-k}, \ldots, x_{0}\right) \in\left(-\infty, \bar{x}_{1}\right]^{k} \times\left[-a / b, \bar{x}_{1}\right]$, then $0 \leq x_{n} \leqslant \bar{x}_{1}$ for $n \geq 1$.

Proof. By part (b) of Lemma 3.1, we have

$$
0=F\left(-a / b, x_{-1}, \ldots, x_{-k}\right) \leq x_{1}=F\left(x_{0}, x_{-1}, \ldots, x_{-k}\right) \leq F\left(\bar{x}_{1}, \bar{x}_{1}, \ldots, \bar{x}_{1}\right)=\bar{x}_{1},
$$

and
$0<F\left(0, x_{-1}, \ldots, x_{-k}\right) \leq x_{2}=F\left(x_{1}, x_{0}, \ldots, x_{-k+1}\right) \leq F\left(\bar{x}_{1}, \bar{x}_{1}, \ldots, \bar{x}_{1}\right)=\bar{x}_{1}$.
Hence, the result follows by induction. The proof is complete.
Theorem 3.2. Assume that $0<a<(A-b)^{2} / 4$ and $A>b>0$ hold. Then the positive equilibrium $\bar{x}$ of Eq.(1.1) is a global attractor with a basin $S=\left(0, \bar{x}_{1}\right)^{k+1}$.

Proof. Let $\left\{x_{n}\right\}$ is a solution of Eq.(1.1) with initial conditions $\left(x_{-k}, \ldots, x_{0}\right) \in$ $S$. Then, by part (b) of Lemma 3.1 and Theorem 3.1, the function $F\left(x_{n}, \ldots, x_{n-k}\right)$ is a strictly increasing function in each of arguments.

By Lemma 3.2, we have $(h(x)-x)(x-\bar{x})<0$. Furthermore, Theorem 1.3 implies that $\bar{x}$ is a global attaractor of all positive solution of Eq.(1.1). Thus

$$
\lim _{n \rightarrow \infty} x_{n}=\bar{x}=\frac{A-b-\sqrt{(A-b)^{2}-4 a}}{2}
$$

The proof is complete.

## 4. THE PRIME PERIOD TWO SOLUTION

In the section, we discuss whether Eq. (1.1) has the prime period two solution.
Theorem 4.1. Assume that $a>0$ and $A>b>0$ hold. Then Eq. (1.1) has no positive solution with prime period two.

Proof. Assume for the sake of contradiction that there exist distinctive positive real numbers $\phi$ and $\varphi$ such that

$$
\ldots, \phi, \varphi, \phi, \varphi, \ldots
$$

is a period two solution of Eq.(1.1). There are two cases to be considered.
Case (a) $k$ is odd. In this case $x_{n+1}=x_{n-k}, \phi$ and $\varphi$ satisfy the system

$$
\phi=\frac{a+b \phi}{A-\varphi}, \quad \varphi=\frac{a+b \varphi}{A-\phi} .
$$

Hence $(\phi-\varphi)(A-b)=0$. According to the condition $A>b>0$, we obtain $\phi=\varphi$, which contradicts the hypothesis $\phi \neq \varphi$.

Case (b) $k$ is even. In this case $x_{n}=x_{n-k}, \phi$ and $\varphi$ statisfy the system

$$
(A-\varphi) \phi=a+b \varphi \text { and }(A-\phi) \varphi=a+b \phi
$$

Subtracting the two equations above, we obtain

$$
(\phi-\varphi)(A+b)=0,
$$

and so $A+b=0$ or $\phi-\varphi=0$, which contradicts the condition $A>b>0$ and the hypothesis of $\phi \neq \varphi$. The proof is complete.

Corollary 4.1. If $A \neq b$, then Eq.(1.1) has no solution with prime period two for all $a \in(0, \infty)$.

## 5. THE CASE $\boldsymbol{A}=0$

In this section, we study the asymptotic stability of the difference equation

$$
\begin{equation*}
x_{n+1}=\frac{b x_{n-k}}{A-x_{n}}, n=0,1 \cdots, \tag{5.1}
\end{equation*}
$$

where $b, A \in(0,+\infty), k \in\{1,2, \ldots\}$ and the initial conditon $x_{-k}, \ldots, x_{0}$ are arbitrary real numbers.

By putting $x_{n}=b y_{n}$, Eq.(5.1) yields

$$
\begin{equation*}
y_{n+1}=\frac{y_{n-k}}{C-y_{n}}, n=0,1 \ldots, \tag{5.2}
\end{equation*}
$$

where $C=A / b>0$. Eq.(5.2) has two equilibria $\bar{y}_{1}=0, \bar{y}_{2}=C-1$. The linearized equation of Eq. (5.2) about the equilibria $\bar{y}_{i}, i=1,2$, is

$$
z_{n+1}-\frac{\bar{y}_{i}}{C-\bar{y}_{i}} z_{n}-\frac{1}{C-\bar{y}_{i}} z_{n-k}=0, i=1,2, n=0,1 \cdots
$$

For $\bar{y}_{2}=C-1$, Theorem 1.2 implies that $\bar{y}_{2}$ is unstable. For $\bar{y}_{1}=0$, we have

$$
\begin{equation*}
z_{n+1}-\frac{1}{C} z_{n-k}=0, n=0,1 \cdots \tag{5.3}
\end{equation*}
$$

The characteristic equation of Eq.(5.3) is $\lambda^{k+1}-1 / c=0$. Hence, by Theorem 1.1, we have
(i) if $A>b$, then $\bar{y}_{1}$ is locally asymptotically stable;
(ii) if $A<b$, then $\bar{y}_{1}$ is a repeller;
(iii) if $A=b$, then linearized stability analysis fails.

In the sequel, we will discuss the global attractivity of the zero equilibrium of Eq. (5.2). So, we assume that $A>b$, namely, $C>1$.

Lemma 5.1. Assume that the initial conditions $\left(y_{-k}, \ldots, y_{0}\right) \in[-C+1, C-1]^{k+1}$. Then $y_{n} \in[-C+1, C-1]$ for $n \geq 1$.

Proof. It is easy to see that

$$
-C+1 \leqslant \frac{-C+1}{C-(-C+1)} \leqslant y_{1}=\frac{y-1}{C-y_{0}} \leqslant \frac{C-1}{C-(C-1)}=C-1,
$$

and

$$
-C+1 \leqslant \frac{-C+1}{C-(-C+1)} \leqslant y_{2}=\frac{y_{0}}{C-y_{1}} \leqslant \frac{C-1}{C-(C-1)}=C-1 .
$$

The result follows by induction, and this completes the proof.
Obviously, Lemma 5.1 implies that the following result is true.
Theorem 5.1. The equilibrium $\bar{y}_{1}=0$ of Eq. (5.2) is a global attractor with a basin $S=[-C+1, C-1]^{k+1}$.

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