# A MATHEMATICAL MODEL FOR TWO POLITICAL PARTIES

Deepak B. Pachpatte<sup>1</sup> and Gajanan S. Solanke<sup>2</sup>

**Abstract:** In this paper, a simple model for two political parties has been proposed. This model involves system of linear differential equations which is solved by using Laplace Transform. Whole population is assumed as constant and homogeneously mixed. Our model is capable of providing numeric results.

*Keywords: Mathematical Modelling, Differential Equations, Laplace Transform. Mathematics Subject Classification:* 00A71, 81T80, 93C15, 44A10.

### 1. INTRODUCTION

Democracy is a system of government by the whole population or all the eligible members of a state, typically through elected representatives. A democracy is a type of political system, or a system of decision making within an institution, or organization, in which all members have the equal share to power. Systems of democracy stand in contrasts to other forms of government, including monarchy and oligarchy.

A political party is a group of people who come together to contest elections and hold power in the government. The party agrees on some proposed policies and programmes, with a view to promoting the collective the good or furthering their supporter's interests. Many political parties have an ideological core, but some do not. In democracies, political parties are elected by the electorate to run a government. Many countries have numerous powerful political parties, such as Germany and India and some nations have oneparty system, such as China and Cuba. The United States is in practice a two-party system, with many smaller parties participating. Its two most powerful parties are the Democratic Party and the Republic Party.

In some studies a non-linear mathematical model for the spread of two political parties has been proposed and analysed by using epidemiological approach [7]. In most of modelling studies statistical methodology is being used by considering that two political parties are competing for the voter's class [3].

Department of Mathematics, Dr. Babasaheb Ambedkar Marathwada University, Aurangabad-431004, (M.S.), India, *E-mail: pachpatte@gmail.com* 

<sup>\*\* 2</sup>CSMSS, Chh. Shahu College of Engineering, Aurangabad-431002, (M.S), India, *E-mail:* gssolanke@gmail.com

In this paper we will discuss the growth and decrease in development of two political parties using mathematical model. In this system we assume that the individuals have right of voting at the age of 18 and all eligible population using the right of voting. We also considered two political parties B and C only, it means an individual must have vote a party B or Party C.

#### 2. MATHEMATICAL MODEL

Let *N* be total population considered in the system. And it is divided into three classes: U(t) =Class containing the population below 18 years old, B(t) =Class containing population which votes to party *B*, C(t) =Class containing the population which votes to party *C*. The entire above are functions of time *t*, from above information we write N(t) = U(t) + B(t) + C(t).

As we know that most worldwide constitutions gives the right of voting to the individuals when they become 18 years old, hence we assume that individuals enters in the class U(t) at the rate  $\mu N$ . Due to inactiveness and death the individuals leaves the class U(t), B(t), C(t) at the rate  $\mu U$ ,  $\mu B$ ,  $\mu C$  respectively. Let us assume that the individuals enter in the class *B* at the rate  $\lambda_{1v}$  and in the class *C* at the rate  $\lambda_{2v}$ . The individuals in class *B* leaves the class and enter in to the class *C* at the rate  $\beta$ 1 and the individuals in class *C* leaves the class and enters into the class *B* at the rate of  $\beta_2$ . The ?ow diagram of the model is as shown in the fig. 1.





The model then consists of three ordinary differential equations of the form

$$\frac{dU}{dt} = \mu N - \lambda_{1\nu} U(t) - \lambda_{2\nu} U(t) - \mu U, \qquad (2.1)$$

$$\frac{dB}{dt} = \lambda_{1\nu}U(t) - \beta_1 B(t) + \beta_2 C(t) - \mu B, \qquad (2.2)$$

$$\frac{dC}{dt} = \lambda_{2\nu} U(t) - \beta_2 C(t) + \beta_1 B(t) - \mu C.$$
(2.3)

Taking Laplace Transform of equation (2.1) we get,

$$sL[U(t)] - U(0) = \frac{\mu N}{s} - \lambda_{1\nu} L[U(t)] - \lambda_{2\nu} L[U(t)] - \frac{\mu U}{s},$$

here we assume, U(0) = 0

therefore,

$$(s + \lambda_{1\nu} + \lambda_{2\nu})L[U(t)] = \frac{\mu N - \mu U}{s},$$
$$L[U(t) = \frac{\mu N - \mu U}{s(s + \lambda_{1\nu} + \lambda_{2\nu})}.$$
(2.4)

Taking Inverse Laplace Transform of equation (2.4) we get,

$$U(t) = \frac{1}{a}(1 - e^{-at}), \qquad (2.5)$$

where,  $a = \lambda_{1v} + \lambda 2v$ .

Now taking Laplace Transform of equation (2.2) we get,

$$s L[B(t)] - B(0) = \lambda_{1\nu} L[U(t)] - \beta_1 L[B(t)] + \beta_2 L[C(t)] - \frac{\mu B}{s},$$

here we assume, B(0) = 0

$$s L[B(t)] = \lambda_{1\nu} L[U(t)] - \beta_1 L[B(t)] + \beta_2 L[C(t)] - \frac{\mu B}{s},$$
  
(s + \beta\_1) L[B(t)] = \lambda\_{1\nu} \frac{\mu N - \mu U}{s(s + \lambda\_{1\nu} + \lambda\_{2\nu})} + \beta\_2 L[C(t)] - \frac{\mu B}{s},  
uN - \mu U = \beta L

$$L[B(t)] = \lambda_{1\nu} \frac{\mu N - \mu U}{s(s + \lambda_{1\nu} + \lambda_{2\nu})(s + \beta_1)} + \frac{\beta_2}{(s + \beta_1)} L[C(t)] - \frac{\mu B}{s(s + \beta_1)}.$$
 (2.6)

Now taking Laplace Transform of equation (2.3) we get,

$$s L[C(t)] - C(0) = \lambda_{2\nu} L[U(t)] - \beta_2 L[C(t)] + \beta_1 L[B(t)] - \frac{\mu C}{s},$$

here we assume, C(0) = 0

$$s L[C(t)] = \lambda_{2\nu} L[U(t)] - \beta_2 L[C(t)] + \beta_1 L[B(t)] - \frac{\mu C}{s},$$

We get,

$$L[C(t)] = \frac{\lambda_{2\nu}}{(s+\beta_2)} L[U(t)] + \frac{\beta_1}{(s+\beta_2)} L[B(t)] - \frac{\mu C}{s(s+\beta_2)}.$$
 (2.7)

Using equations (2.4) and (2.6) in equation (2.7) we get,

$$L[C(t)] = \frac{\lambda_{2v}}{(s+\beta_2)} \frac{\mu N - \mu U}{s(s+\lambda_{1v}+\lambda_{2v})} + \frac{\beta_1}{(s+\beta_2)} \left(\lambda_{1v} \frac{\mu N - \mu U}{s(s+\lambda_{1v}+\lambda_{2v})(s+\beta_1)} + \frac{\beta_2}{(s+\beta_1)} L[C(t)] - \frac{\mu B}{s(s+\beta_1)}\right) - \frac{\mu C}{s(s+\beta_2)},$$

$$= \frac{\lambda_{2v} (\mu N - \mu U)}{s(s + \lambda_{1v} + \lambda_{2v})(s + \beta_2)} + \frac{\beta_1 \lambda_{1v} (\mu N - \mu U)}{s(s + \lambda_{1v} + \lambda_{2v})(s + \beta_1)(s + \beta_2)} + \frac{\beta_1 \beta_2}{(s + \beta_1)(s + \beta_2)} L[C(t)] - \frac{\beta_1 \mu B}{s(s + \beta_1)(s + \beta_2)} - \frac{\mu C}{s(s + \beta_2)},$$

(2.8)

From above equation (2.8),

$$L[C(t)] - \frac{\beta_{1}\beta_{2}}{(s+\beta_{1})(s+\beta_{2})}L[C(t)] \\= \frac{\lambda_{2v} (\mu N - \mu U)}{s(s+\lambda_{1v}+\lambda_{2v})(s+\beta_{2})} + \frac{\beta_{1}\lambda_{1v} (\mu N - \mu U)}{s(s+\lambda_{1v}+\lambda_{2v})(s+\beta_{1})(s+\beta_{2})} \\- \frac{\beta_{1}\mu B}{s(s+\beta_{1})(s+\beta_{2})} - \frac{\mu C}{s(s+\beta_{2})'}$$

$$\begin{pmatrix} 1 - \frac{\beta_1 \beta_2}{(s + \beta_1)(s + \beta_2)} \end{pmatrix} L[C(t)] \\ = \frac{\lambda_{2v} (\mu N - \mu U)}{s(s + \lambda_{1v} + \lambda_{2v})(s + \beta_2)} + \frac{\beta_1 \lambda_{1v} (\mu N - \mu U)}{s(s + \lambda_{1v} + \lambda_{2v})(s + \beta_1)(s + \beta_2)} \\ - \frac{\beta_1 \mu B}{s(s + \beta_1)(s + \beta_2)} - \frac{\mu C}{s(s + \beta_2)'}$$

$$\begin{pmatrix} (s+\beta_1)(s+\beta_2) - \beta_1\beta_2 \\ (s+\beta_1)(s+\beta_2) \end{pmatrix} L[C(t)] \\ = \frac{\lambda_{2v} (\mu N - \mu U)}{s(s+\lambda_{1v} + \lambda_{2v})(s+\beta_2)} + \frac{\beta_1\lambda_{1v} (\mu N - \mu U)}{s(s+\lambda_{1v} + \lambda_{2v})(s+\beta_1)(s+\beta_2)} \\ - \frac{\beta_1\mu B}{s(s+\beta_1)(s+\beta_2)} - \frac{\mu C}{s(s+\beta_2)'}$$

This gives,

$$L[C(t)] = \frac{(s+\beta_1)(s+\beta_2)}{(s+\beta_1)(s+\beta_2) - \beta_1\beta_2} \frac{\lambda_{2\nu}(\mu N - \mu U)}{s(s+\lambda_{1\nu} + \lambda_{2\nu})(s+\beta_2)} + \frac{(s+\beta_1)(s+\beta_2)}{(s+\beta_1)(s+\beta_2) - \beta_1\beta_2} \frac{\beta_1\lambda_{1\nu}(\mu N - \mu U)}{s(s+\lambda_{1\nu} + \lambda_{2\nu})(s+\beta_1)(s+\beta_2)} - \frac{(s+\beta_1)(s+\beta_2) - \beta_1\beta_2}{(s+\beta_1)(s+\beta_2) - \beta_1\beta_2} \frac{\beta_1\mu B}{s(s+\beta_1)(s+\beta_2)} - \frac{(s+\beta_1)(s+\beta_2) - \beta_1\beta_2}{(s+\beta_1)(s+\beta_2) - \beta_1\beta_2} \frac{\mu C}{s(s+\beta_2)'}$$

$$= \frac{\lambda_{2\nu}(\mu N - \mu U)(s + \beta_1)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[(s + \beta_1)(s + \beta_2) - \beta_1\beta_2]} + \frac{\beta_1\lambda_{1\nu}(\mu N - \mu U)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[(s + \beta_1)(s + \beta_2) - \beta_1\beta_2]} - \frac{\beta_1\mu B}{s[(s + \beta_1)(s + \beta_2) - \beta_1\beta_2]} - \frac{\mu C(s + \beta_1)}{s[(s + \beta_1)(s + \beta_2) - \beta_1\beta_2]},$$

$$= \frac{\lambda_{2\nu}(\mu N - \mu U)(s + \beta_1)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[s^2 + (\beta_1 + \beta_2)s]} + \frac{\beta_1 \lambda_{1\nu}(\mu N - \mu U)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[s^2 + (\beta_1 + \beta_2)s]} - \frac{\beta_1 \mu B}{s[s^2 + (\beta_1 + \beta_2)s]} - \frac{\mu C(s + \beta_1)}{s[s^2 + (\beta_1 + \beta_2)s]'}$$
$$= \lambda_{2\nu}(\mu N - \mu U)(s + \beta_1) + \beta_1 \lambda_{1\nu}(\mu N - \mu U) - \beta_1 \mu B + \mu C(s + \beta_1)$$
(2.6)

$$=\frac{\lambda_{2\nu}(\mu N - \mu U)(s + \beta_1) + \beta_1 \lambda_{1\nu}(\mu N - \mu U)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[s^2 + (\beta_1 + \beta_2)s]} - \frac{\beta_1 \mu B + \mu C(s + \beta_1)}{s[s^2 + (\beta_1 + \beta_2)s]}.$$
(2.9)

Let

$$\lambda_{2v}(\mu N - \mu U) = a, \quad \beta_1 \lambda_{1v}(\mu N - \mu U) = b, \quad \lambda_{1v} + \lambda_{2v} = c, \quad \beta_1 + \beta_2 = d,$$
  
$$\beta_1 \mu B = e, \quad \mu C = f$$
  
$$L[C(t)] = \frac{a(s + \beta_1) + b}{s(s + c)[s^2 + ds]} - \frac{e + f(s + \beta_1)}{s[s^2 + ds]}.$$
 (2.10)

Taking Inverse Laplace Transform of equation (2.10) we get,

$$C(t) = \frac{(2e - 2df + 2f\beta_1)\sinh\left(\frac{dt}{2}\right)}{d^2}e^{\left(\frac{-dt}{2}\right)} + \frac{(-ad + a\beta_1 + b)}{d^2(c - d)}e^{-dt} + \frac{(ac - a\beta_1 - b)}{c^2(c - d)}e^{-ct} + \frac{-cd(ce + cf\beta_1 - a\beta_1 - b)t + acd - ac\beta_1 - bc - ad\beta_1 - bd}{c^2d^2},$$
(2.11)

where,

$$\begin{split} a &= \lambda_{2v}(\mu N - \mu U), \qquad b = \beta_1 \lambda_{1v}(\mu N - \mu U), \qquad c = \lambda_{1v} + \lambda_{2v}, \quad d = \beta_1 + \beta_2, \\ e &= \beta_1 \mu B, \qquad f = \mu C. \end{split}$$

Using equation (2.7) in equation (2.6) we have,

$$L[B(t)] = \lambda_{1\nu} \frac{\mu N - \mu U}{s(s + \lambda_{1\nu} + \lambda_{2\nu})(s + \beta_1)} + \frac{\beta_2}{(s + \beta_1)} \left(\frac{\lambda_{2\nu}}{(s + \beta_2)} L[U(t)] + \frac{\beta_1}{(s + \beta_2)} L[B(t)] - \frac{\mu C}{s(s + \beta_2)}\right) - \frac{\mu B}{s(s + \beta_1)}.$$
(2.12)

Using equation (2.4) in equation (2.12) we get,

$$\begin{split} L[B(t)] &= \lambda_{1\nu} \frac{\mu N - \mu U}{s(s + \lambda_{1\nu} + \lambda_{2\nu})(s + \beta_1)} \\ &+ \frac{\beta_2}{(s + \beta_1)} \Big( \frac{\lambda_{2\nu}}{(s + \beta_2)} \frac{\mu N - \mu U}{s(s + \lambda_{1\nu} + \lambda_{2\nu})} + \frac{\beta_1}{(s + \beta_2)} L[B(t)] - \frac{\mu C}{s(s + \beta_2)} \Big) \\ &- \frac{\mu B}{s(s + \beta_1)'} \\ &= \frac{\lambda_{1\nu}(\mu N - \mu U)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})(s + \beta_1)} + \frac{\beta_2 \lambda_{2\nu}(\mu N - \mu U)}{s(s + \beta_1)(s + \beta_2)(s + \lambda_{1\nu} + \lambda_{2\nu})} \end{split}$$

$$+\frac{\beta_{1}\beta_{2}}{(s+\beta_{1})(s+\beta_{2})}L[B(t)] - \frac{\beta_{2}\mu C}{s(s+\beta_{1})(s+\beta_{2})} - \frac{\mu B}{s(s+\beta_{1})}.$$
(2.13)

This implies,

$$\begin{pmatrix} 1 - \frac{\beta_1 \beta_2}{(s+\beta_1)(s+\beta_2)} \end{pmatrix} L[B(t)] \\ = \frac{\lambda_{1\nu}(\mu N - \mu U)}{s(s+\lambda_{1\nu}+\lambda_{2\nu})(s+\beta_1)} + \frac{\beta_2 \lambda_{2\nu}(\mu N - \mu U)}{s(s+\beta_1)(s+\beta_2)(s+\lambda_{1\nu}+\lambda_{2\nu})} \\ - \frac{\beta_2 \mu C}{s(s+\beta_1)(s+\beta_2)} - \frac{\mu B}{s(s+\beta_1)}.$$
(2.14)

Therefore,

$$L[B(t)] = \frac{\lambda_{1\nu}(\mu N - \mu U)(s + \beta_2)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[s^2 + s(\beta_1 + \beta_2)]} + \frac{\beta_2 \lambda_{2\nu}(\mu N - \mu U)}{s(s + \lambda_{1\nu} + \lambda_{2\nu})[s^2 + s(\beta_1 + \beta_2)]} - \frac{\beta_2 \mu C}{s[s^2 + s(\beta_1 + \beta_2)]} - \frac{\mu B(s + \beta_2)}{s[s^2 + s(\beta_1 + \beta_2)]}.$$
(2.15)

Let  $\lambda_{1\nu} (\mu N - \mu U) = a$ ,  $\beta_2 \lambda_{2\nu} (\mu N - \mu U) = b$ ,  $\beta_1 + \beta_2 = c$ ,  $\lambda_{1\nu} + \lambda_{2\nu} = d$ ,  $\beta_2 \mu C = e$ ,  $\mu B = f$ .

$$L[B(t)] = \frac{a(s+\beta_2)}{s(s+d)[s^2+sc]} + \frac{b}{s(s+d)[s^2+sc]} - \frac{e}{s[s^2+sc]} - \frac{f(s+\beta_2)}{s[s^2+sc]'}$$
$$= \frac{a(s+\beta_2) + b - e(s+d) - f(s+\beta_2)(s+d)}{s(s+d)[s^2+sc]}.$$
(2.16)

Taking inverse Laplace Transform of equation (2.16) we get,

$$B(t) = \frac{(de - a\beta_2 - b + df\beta_2 - cdf - ce - cf\beta_2 + c^2f + ac)}{c^2(c - d)}e^{-ct} + \frac{(a\beta_2 + b - ad)}{d^2(c - d)}e^{-dt} + \frac{(a\beta_2 + b - de - f\beta_2d)t}{cd} + \frac{acd - ac\beta_2 - bc - d^2cf + ed^2 - ad\beta_2 - bd + f\beta_2d^2}{c^2d^2},$$
(2.17)

where,

$$\begin{aligned} a &= \lambda_{1v}(\mu N - \mu U), \qquad b &= \beta_2 \lambda_{2v}(\mu N - \mu U), \qquad c &= \beta_1 + \beta_2, \\ d &= \lambda_{1v} + \lambda_{2v}, \quad e &= \beta_2 \mu C, \qquad f &= \mu B. \end{aligned}$$

The equations (2.5), (2.11), (2.17) are the required solution of the system of linear differential equations (2.1), (2.2), (2.3).

#### 3. NUMERICAL EXPERIMENTS

In this section, numerical results are presented. Our aim is to show which factor is more important as compared to other by considering some parameters. We consider three different examples.

## 3.1. Example 1

Let us assume that,  $\lambda_{1\nu} = 0.59$ ,  $\lambda_{2\nu} = 0.35$ ,  $\beta_1 = 0.142$ ,  $\beta_2 = 0.1$ ,  $\mu N = 0.20$ ,  $\mu U = \mu B = \mu C = 0.008$ 



Figure 3: Graph for political party C

# 3.2. Example 2

Let us assume that,  $\lambda_{1\nu} = 0.58$ ,  $\lambda_{2\nu} = 0.42$ ,  $\beta_1 = 0.1$ ,  $\beta_2 = 0.1$ ,  $\mu N = 0.30$ ,  $\mu U = \mu B = \mu C = 0.008$ 



Figure 5: Graph for political party C

# 3.3. Example 3

Let us assume that,  $\lambda_{1\nu} = 0.5$ ,  $\lambda_{2\nu} = 0.5$ ,  $\beta_1 = 0.2$ ,  $\beta_2 = 0.1$ ,  $\mu N = 0.30$ ,  $\mu U = \mu B = \mu C$ = 0.008



Figure 7: Graph for political party C

## 4. CONCLUSION

In this we have studied a mathematical model for two political parties, with numerical examples. It shows that the main affecting factor in growth of political party are (i) New voters (ii) Voters which changes party from one to another. Other factors (like death and inactiveness) are negligible.

In example 1 graph of party C increases faster than that of graph of party B. In this example  $\lambda_{1\nu}$  is greater than  $\lambda_{2\nu}$  by 0.24 but the factor  $\beta_1$  is greater than  $\beta_2$  by 0.042. In example 2 graph of party B increases faster than that of graph of party C. In this example  $\lambda_{1\nu}$  is greater than  $\lambda_{2\nu}$  by 0.16 but the factor  $\beta_1 = \beta_2$ . And In example 3 graph of party C increases faster than that of graph of party B. In this example  $\lambda_{1\nu} = \lambda_{2\nu}$  and  $\beta_1$  is greater than  $\beta_2$  by 0.1.

The factors  $\beta_1$ ,  $\beta_2$  are more effective than the factors  $\lambda_{1\nu}$ ,  $\lambda_{2\nu}$  i.e. the rate at which the voters changes the party from one to another is more effective than the rate at which the new voters enters in political party. In order to increase no. of voters in political party the factors  $\beta_1$ , and  $\beta_2$  must be considered.

#### References

- S. Banerjee Mathematical Modelling: Models, Analysis and Applications, CRC Press, New York, (2014).
- [2] B. Barnes and G. R. Fulford, Mathematical Modelling With Case Studies, Second Edition, CRC Press, UK, (2009).
- [3] A.S. Belenky, D.C. King, A mathematical model for estimating the potential margin of state undecided voters for a candidate in a US Federal election, Mathematical and Computer Modelling, 45(5-6)(2007), 585- 593.
- [4] G. Dangelmayr and M. Kirby Mathematical Modelling, A ComprehensiveIntroduction, Prentice Hall, New Jersey.
- [5] K. Diethelm, A fractional calculus based model for the simulation of anoutbreak of dengue fever, Nonlinear Dynamics, (71) (2013), 613-619.
- [6] J. N. Kapur, Mathematical Modelling, New Age International, (1988).
- [7] A. K. Mishra, A simple mathematical model for the spread of two political parties, Nonlinear Analysis: Modelling and Control, 17(3) (2012), 343-354.
- [8] S. P. Otto, T. Day, A Biological Guide to Mathematical Modelling in Ecology and Evaluation, Princeton University Press, (2007).