

# Closed Loop Controlled Forward Converter with Simple Auxiliary Resonant Soft Switching

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**Abstract :** In this paper, the closed loop control of zero-current soft switched pulse width modulation based forward converter is implemented using the proportional & integral (PI) controller. The zero current switching (ZCS) for the main switch of forward converter is achieved by a simple auxiliary circuit consisting of an auxiliary switch and capacitor and auxiliary circuit is also used to reset the transformer core. Another advantage of this converter over conventional ZCS forward converter is that additional inductor is not required to reset the transformer core and the leakage inductance of transformer itself is used as a resonant inductor. Also auxiliary switch is soft switched. The proposed converter is operated in closed loop for obtaining the desired output voltage by having a control over duty ratio of the main switch using a conventional proportional and integral controller. The converter performance is analyzed with the simulation results done in MATLAB simulink environment.

**Keywords :** Forward converter, soft switching, pwm technique PI controller.

## 1. INTRODUCTION

In various applications, there is a necessity of dc power supplies which is fulfilled by the isolated converters namely, fly back and forward converters. These are mostly used in low power applications because of small count in elements and simple in structure. High voltages are observed across the switch during turn off period, due to the transformers leakage inductance. The voltage spikes and switching losses can be reduced by using RCD (resistor-capacitor-diode) clamps and snubbers. The zero voltage switching and zero current switching conditions are achieved for forward converters by using active snubber and clamps. Many methods are introduced to provide ZCS for main and auxiliary switches, but these methods require a reset winding and inductor in the auxiliary circuit [12] and [13]. Even then the main switch is not fully soft switched because of presence of large magnetizing inductance during turn off instant. In addition to reduce the switching losses, the voltage is to be controlled as per the requirement. Thus the soft switched converter is operated in closed loop with proportional – integral controller to achieve the tight voltage regulation by obtaining the desired voltage as output of the converter.

In this paper, a simple auxiliary circuit consisting of an auxiliary switch and auxiliary capacitor is used on the secondary side of isolated transformer to provide ZCS condition. This ZCS condition is employed for both main switch and auxiliary switch also. Additional advantage of this converter is there is no need of using a reset winding and the leakage inductance of the transformer is used in

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resonance with the capacitor to reset the transformer core. As compared with active clamp method of soft switching this method is not load dependent, *i.e.*, the auxiliary circuit elements are designed for nominal load, so that the zcs condition can be employed under any load conditions. These along with this soft switching the load put voltage is controlled by generating a required duty ratio from the PI controller with closed loop operation. The converter is analyzed in section-II. closed loop operation for this converter is discussed in section-III and the simulation study of this soft switched converter in closed loop is discussed in section-IV.

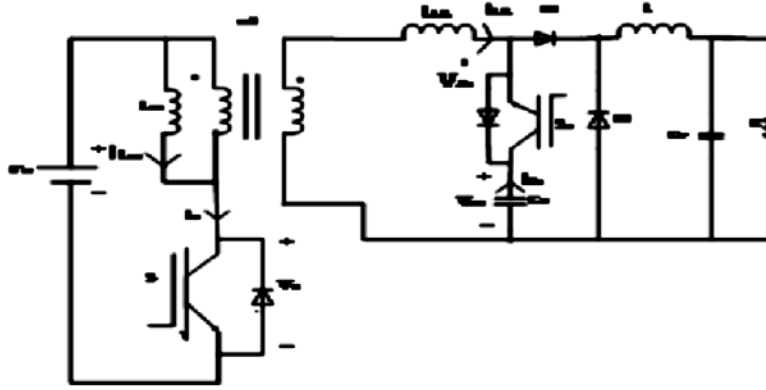


Fig. 1. ZCS soft switched forward converter with auxiliary circuit.

## 2. MATHEMATICAL ANALYSIS OF ZCS FORWARD CONVERTER

The soft switched converter with the simple auxiliary circuit consists of main switch  $S_a$ , Diodes  $D_1$  and  $D_2$ , Filter inductance  $L$ , ideal transformer  $T$  with  $n:1$  turns ratio, leakage inductance  $L_l$  and magnetizing inductance  $L_m$ . The auxiliary circuit having elements are auxiliary switch  $S_a$  and auxiliary capacitor  $C_a$ . For simple analysis, input voltage is considered as constant and is equal to  $V_{in}$  and also output inductor current is assumed constant and is equal to  $I_o$ . Thus the operation of this soft switched converter is explained in ten modes over a switching cycle. The following assumptions are made before analyzing the operation of the circuit as  $C_a$  charged to  $2V_{in}/n$ . The auxiliary switch is off and the diode  $D_1$  and main switches are conducting.

**Mode 1  $[t_0 - t_1]$  :** In this interval, the main switch conducts and carries a current of  $I_o/n + I_{lm}$ . This mode starts with the auxiliary switch turn on and begins the resonance condition between auxiliary capacitor and leakage inductance and transformer. As the capacitor voltage is greater than  $V_{in}/n$ , the leakage inductance current of the transformer ( $I_{lk}$ ) falls to zero and the main switch current also decreases to  $I_{lm}$ . Thus the leakage inductance current and the voltage of auxiliary switch in the mode are defined as Equation 1, 2 & 3.

$$I_{LL} = I_o \frac{\left( \frac{2V_{in}}{n} \right) - \left( \frac{V_{in}}{n} \right)}{Z_o} \sin(\omega_0 (t - t_0)) \tag{1}$$

$$V_{c_a} = \frac{V_{in}}{n} + \left( \frac{2V_{in}}{n} - \frac{V_{in}}{n} \right) \cos(\omega_0 (t - t_0)) \tag{2}$$

where  $Z_o = \sqrt{\frac{L_l}{C_a}}, \omega_0 = \frac{1}{\sqrt{L_l C_a}} \tag{3}$

**Mode 2  $[t_1 - t_2]$  :** In this interval, the resonance between the leakage inductance and auxiliary capacitor continues and makes the leakage current negative. This in turn falls, the main switch current from  $I_{lm}$  to zero. This mode ends by observing the leakage inductor current falls to  $-nI_{lm}$ . (Thus the same equations are applied for inductance current and capacitor voltage in this mode also).

**Mode 3**  $[t_2 - t_3]$  : In this interval of operation, the magnitude of leakage inductance current is higher. Then  $nI_{Lm}$  with the opposite direction and the body diode of the main switch conducts current. Then, in the period, the main switch can be turned off with zcs condition. Thus, the same equations are applied for inductance current and capacitor voltage in this mode also. at the end of this mode, the auxiliary capacitor voltage reaches to  $V_1$ , which is less than  $V_{in}/n$  and  $-nI_{lm}$  is the current into leakage inductance at the end of the interval.

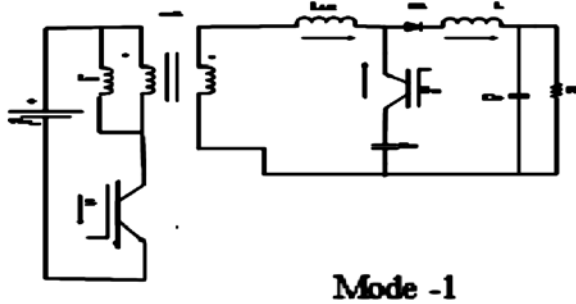


Fig. 2 Equivalent circuit of the converter in mode 1.

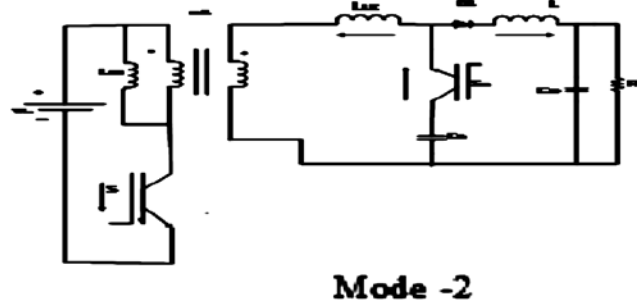


Fig.3 Equivalent circuit of the converter in mode 2,

**Mode 4**  $[t_3 - t_4]$  : In this interval, the leakage inductance current is constant and equals to  $-nI_{lm}$ , the auxiliary capacitor discharges with constant current equal to  $nI_{lm} + I_0$  until its voltage becomes zero. This mode ends when  $V_{ca}$  reaches to zero. Then the diode  $D_2$  is forward biased and starts carrying current at zvs. Thus, at the end of this mode diode  $D_1$  turns off at zvs. The auxiliary capacitor voltage in this mode is given by equation (4).

$$V_{C_a} = V_1 - \frac{I_0 + nI_{Lm}}{C_a}(t - t_3) \tag{4}$$

**Mode 5**  $[t_4 - t_5]$  : In this interval, the resonance starts between the auxiliary capacitor and leakage inductance and magnetizing inductance of transformer. In this mode, during resonance  $L_m$  current falls to zero and thus resets the transformer core. also  $D_2$  conducts the output inductor current. The equations for magnetizing current and capacitor voltage in this mode are given by eq(5),eq(6) & eq(7).

$$I_{L_m} = \bar{I}_{L_m} \cos(\omega_1(t - t_4)) \tag{5}$$

$$V_{C_a} = -Z_1 n \bar{I}_{L_m} \sin(\omega_1(t - t_4)) \tag{6}$$

Where 
$$Z_1 = \sqrt{\frac{L_m}{n^2 C_a}}, \omega_1 = \frac{n}{\sqrt{L_m C_a}} \tag{7}$$

The following assumptions are made before analyzing the operation of the circuit as  $C_a$  charged to  $2 V_{in}/n$ . The auxiliary switch is off and the diode  $D_1$  and main switches are conducting.

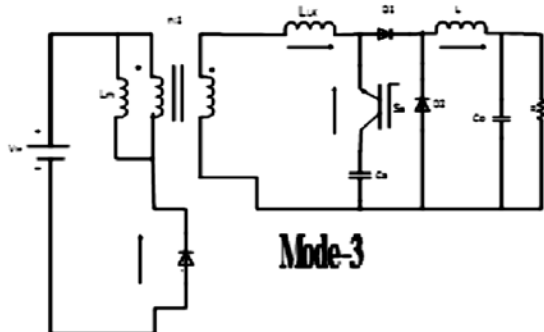


Fig. 4. Equivalent circuit of the converter in mode 3.

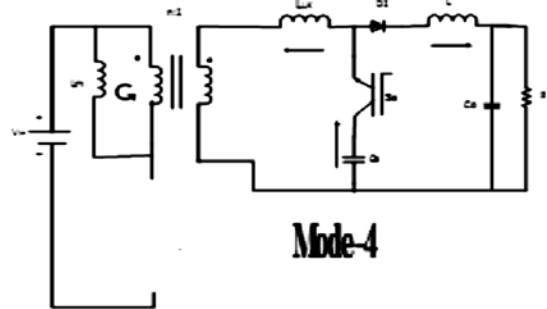


Fig. 5. Equivalent circuit of the converter in mode 4.

**Mode 6** [ $t_5 - t_6$ ] : In this interval the resonance between auxiliary capacitor  $C_a$  and magnetizing inductance  $L_m$  continues through the body diode of auxiliary switch. The auxiliary capacitor voltage rises from its initial value  $-nI_{lm}Z_1$  (then, the same equations are applied for inductance current capacitor voltage in this mode also. Therefore, at the end of the mode, the magnetizing inductance current is zero and  $C_a$  maintains constant voltage equals to  $-nI_{lm}Z_1$ . Therefore, at the end of the mode, the magnetizing inductance current is zero and  $C_a$  maintains constant voltage equals to  $-nI_{lm}Z_1$ .

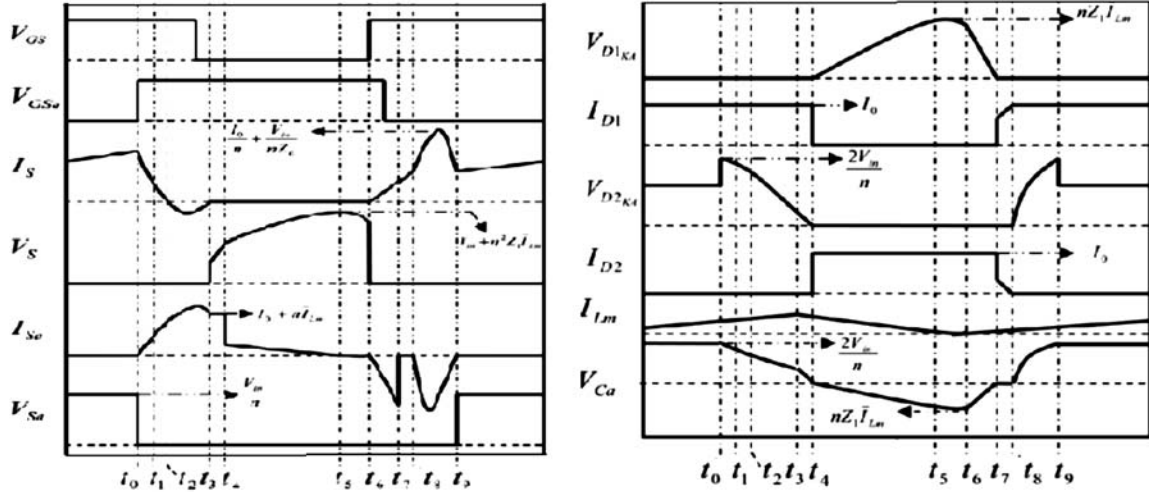


Fig. 6. Theoretical model waveforms of the converter.

**Mode 7** [ $t_6 - t_7$ ] : This interval starts by turn on of main switch. This makes the  $V_{in}$  placed across the transformer primary and resonance starts between the  $C_a$  and the transformer leakage inductance. The voltage of auxiliary capacitor rises from its negative value towards to zero and the current in leakage inductance of the transformer raises to  $I_1$ .

$$I_{LL} = \frac{\left(\frac{V_{in}}{n}\right) + Z_1 n \bar{I}_{Lm}}{z_0} \sin(w_0(t - t_6)) \tag{8}$$

$$V_{C_a} = -Z_1 n \bar{I}_{Lm} + \left(\frac{V_{in}}{n} + Z_1 n \bar{I}_{Lm}\right) * (-\cos(w_0(t - t_6)) + 1) \tag{9}$$

**Mode 8** [ $t_7 - t_8$ ] : This interval starts when auxiliary capacitor voltage reaches to zero and diode  $D_1$  starts conducting current. As diode  $D_2$  is conducting, the capacitor voltage remains zero. In this mode, the secondary voltage is  $V_{in} / n$  and the leakage inductance current increases linearly from  $I_1$  to  $I_0$ . At the end of this mode diode  $D_2$  turns off. The leakage inductance current is given by

$$I_{LL} = I_1 + \frac{V_{in}(t - t_7)}{n.L_L} \tag{10}$$

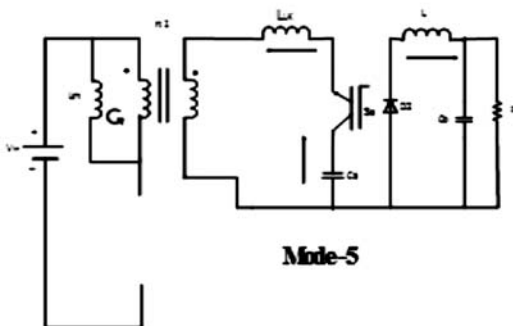


Fig. 7. Equivalent circuit of the converter in mode 5.

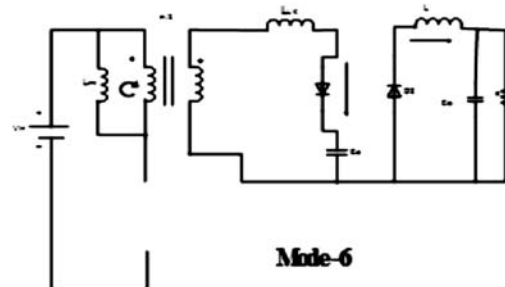


Fig. 8. Equivalent circuit of the converter in mode 6.

**Mode 9 [ $t_8 - t_9$ ]** : In this mode of operation, the resonance is occurred with leakage inductance and capacitor through the body diode of auxiliary switch. Thus, the auxiliary switch  $S_a$  can be now turned off at any time during this interval under ZVS. At the end of this mode, the capacitor voltage  $V_{Ca}$  is equal to  $2V_{in} / n$ . Half of the resonance period formed by  $C_a$  and  $L_L$  is the duration of this interval. Thus, the equations for  $I_{LL}$  and  $V_{Ca}$  is given by

$$I_{LL} = \frac{V_{in}}{nz_0} \sin(\omega_0(t - t_8)) \quad (11)$$

$$V_{C_a} = V_{in} - V_{in} \cos(\omega_0(t - t_8)) \quad (12)$$

**Mode 10 [ $t_9 - t_0 + T$ ]**: The main switch is turned on in this mode and the converter operates like a normal PWM forward converter. Duration of this mode is  $D \cdot T$ , where  $D$  is the duty ratio and  $T$  is the switching period. The equation for the magnetizing current at the end of this interval is given by

$$I_{L_m} = \frac{V_{in} \cdot D \cdot T}{L_m} \quad (13)$$

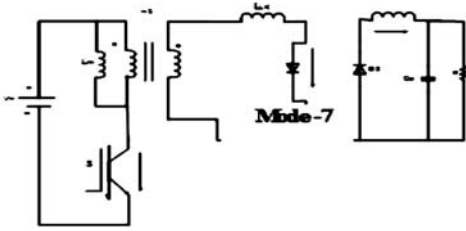


Fig. 9. Equivalent circuit of the converter in mode 7.

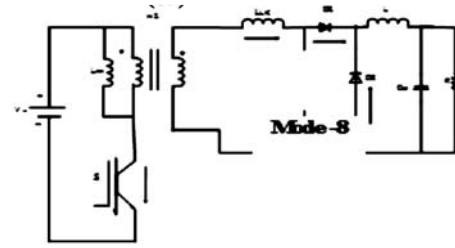


Fig. 10. Equivalent circuit of the converter in mode 8.

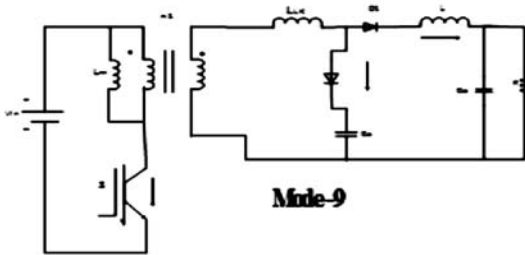


Fig. 11. Equivalent circuit of the converter in mode 9.

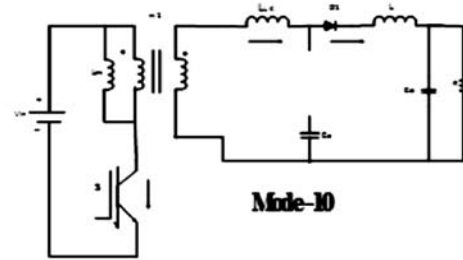


Fig. 12. Equivalent circuit of the converter in mode 10.

### 3. DESIGN OF THE ZCS FORWARD CONVERTER

Table 1. Parameters of the ZVS-QR Buck converter.

Parameter	Symbol	Value
Input voltage	$V_s$	150V
Output voltage	$V_0$	32V
Power	$P_0$	200W
Switching frequency	$f_s$	100 KHz
Magnetizing Inductance	$L_m$	1 mH
Transformer turns ratio	$n : 1$	2
Duty cycle	$D$	0.45
Auxiliary capacitor	$C_a$	22nF
Leakage inductance in secondary side	$L_l$	2 $\mu$ H

In this section the design of ZCS Forward converter, reducing the voltage from 150V to 32V operated at 100 KHz is given in detail. Table 1 shows the parameters of the ZCS forward converter with an auxiliary circuit.

As per the analysis of the converter in section II, the equation that should be satisfied to get the ZCS of the main switch in mode 2 operation is

$$\frac{(2V_{in}/n) - (V_{in}/n)}{Z_0} \geq I_0 + nI_{Lm} \quad (14)$$

The selection of the auxiliary capacitor is given from two basic conditions given by equations (15) and (16).

$$C_a \geq \frac{L_L n^2 (I_0 + nI_{Lm})^2}{V_m^2} \quad (15)$$

$$C_a \leq \frac{4n^2 (1-D)^2 T^2}{\pi^2 L_m} \quad (16)$$

#### 4. CLOSED LOOP CONTROL OF ZCS FORWARD CONVERTER

In this section the closed loop control of ZCS forward converter is given and Fig.13 shows the block diagram of the converter with PI controller.

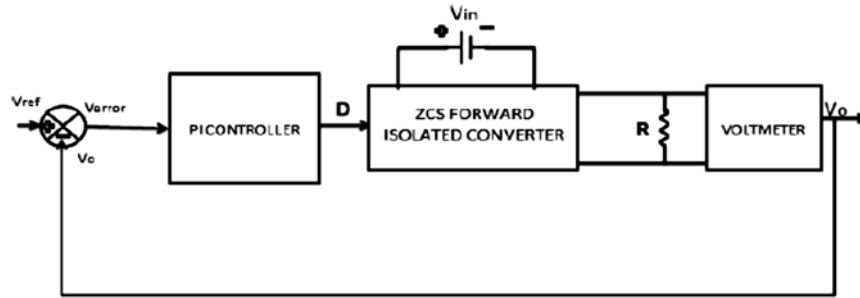


Fig. 13. Block diagram of PI controlled converter.

A proportional–integral controller is a generic control loop feedback mechanism widely used in industrial control systems. A PI controller calculates an “error” value as the difference between a measured process variable and a desired set point. The controller attempts to minimize the error by adjusting the process control inputs.

The proportional and integral terms are summed to calculate the output of the PI controller. Defining  $u(t)$  as the controller output, the final form of the PI algorithm is

$$u(t) = K_p e(t) + K_i \int e(t) dt \quad (17)$$

Where, the error  $e(t)$  is the difference between command and plant output, and it is the controller input; the control variable  $u(t)$  is the controller output. Performing Laplace transform on above equation,

$$G(s) = K_p \left( 1 + \frac{1}{ST_i} \right) \text{ and } G(s) = K_p + \frac{K_i}{S} \quad (18)$$

The PI controller calculation (algorithm) involves two separate constant parameters the proportional, the integral values, denoted P, I. heuristically, these values can be interpreted in terms of time: P depends on the present error, I on the accumulation of past errors. The weighted sum of these two actions is used to adjust the process via a control element such as duty ratio of pulse generator.

A proportional controller ( $K_p$ ) will have the effect of reducing the rise time and will reduce, but never eliminate, the steady-state error. An integral control ( $K_i$ ) will have the effect of eliminating the steady-state error, but it may make the transient response worse.

### 5. SIMULATION RESULTS

Fig. 14 represents the Simulink diagram of the ZCS forward converter with simple auxiliary circuit used to reduce the Voltage from 150v to 32v with 200W output Simulink model of ZCS forward converter with simple auxiliary circuit.

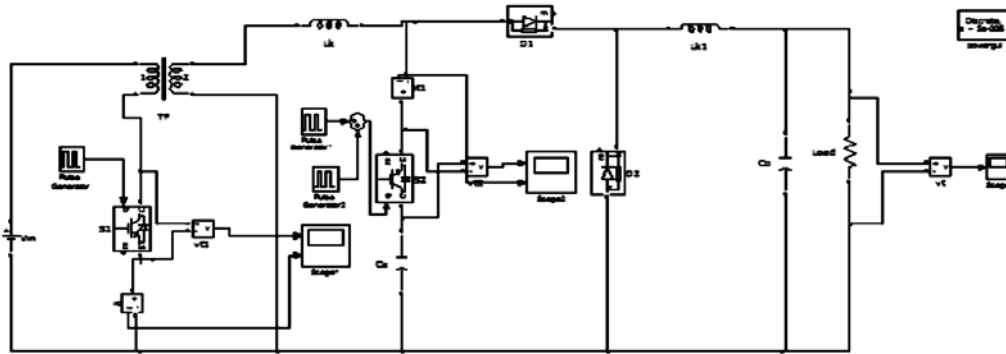


Fig. 14. Simulink model of ZCS forward converter with simple auxiliary circuit.

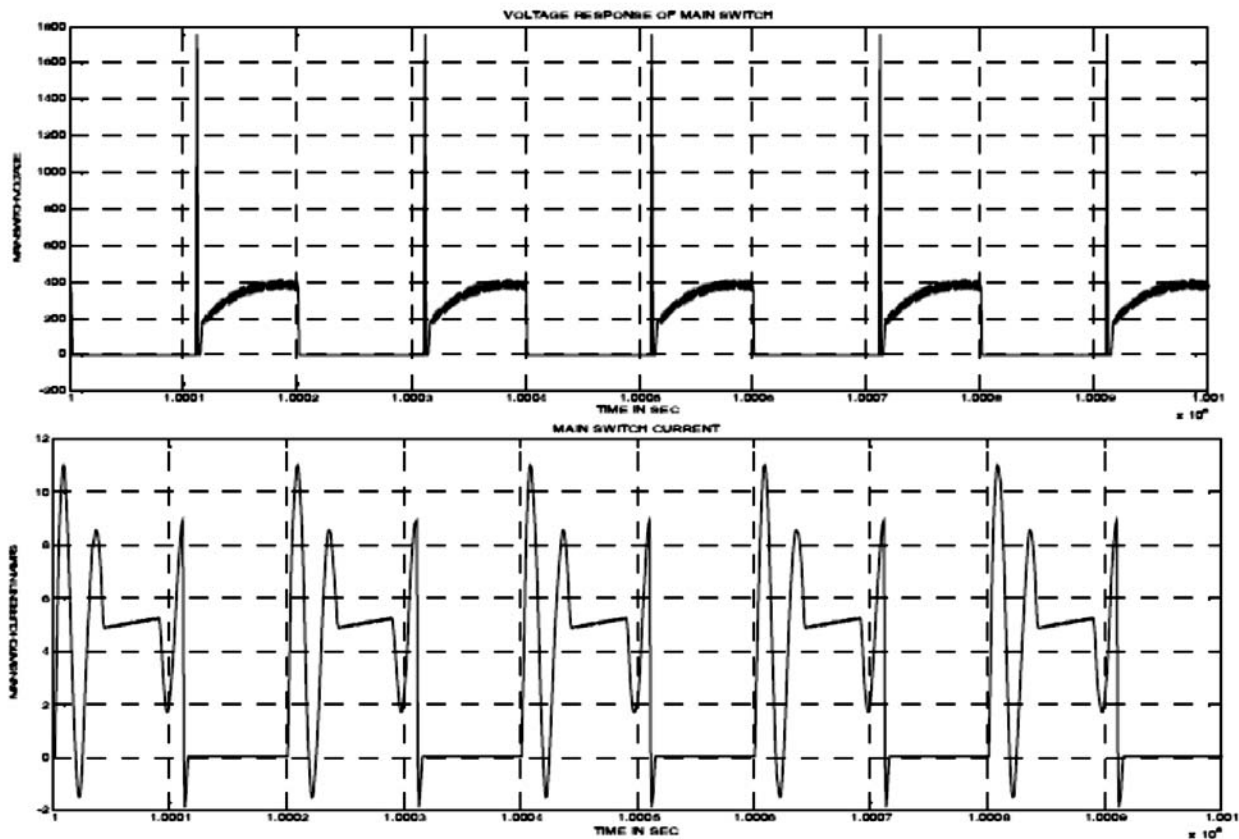


Fig. 15. Main switch voltage and current responses of ZCS forward converter.

Fig.15 shows the voltage and current waveforms of main switch, and from section II the  $V_s$  is  $V_s = V_{in} + n^2 Z_1 \overline{I_{Lm}}$  gives 310V and the peak value of switch current as  $(I_0/n) + (V_{in}/nZ_0)$  gives 10.99A

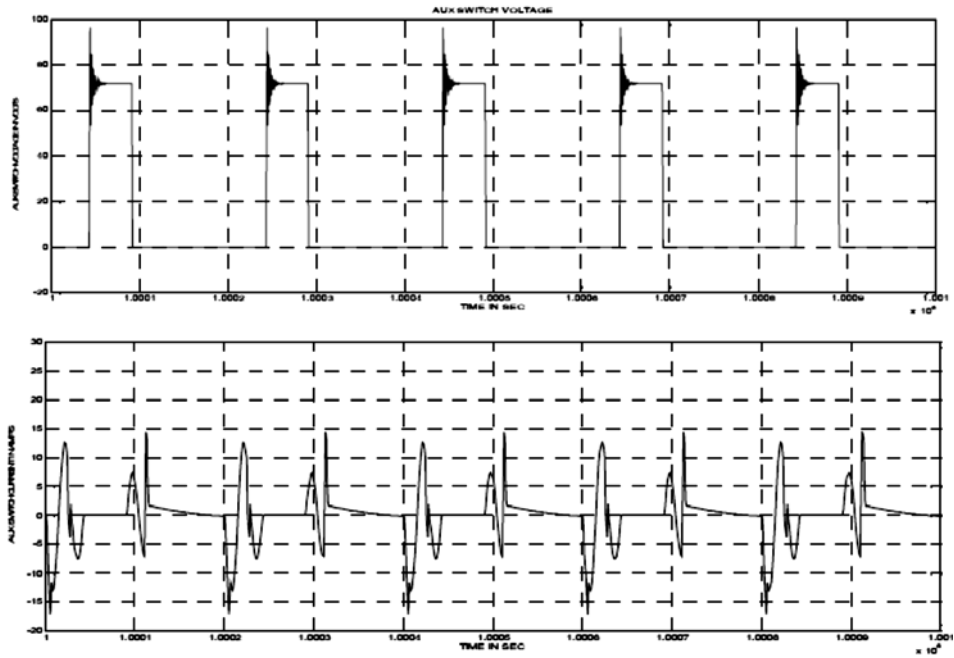


Fig. 16. Auxiliary switch voltage and current responses of ZCS forward converter.

Fig.16 shows the voltage and current waveforms of auxiliary switch, and from section II the  $V_{sa} = \frac{V_{in}}{n}$  gives 75V under steady state and the peak value of switch current as  $I_0 + nI_{Lm}$  gives 6.925A.

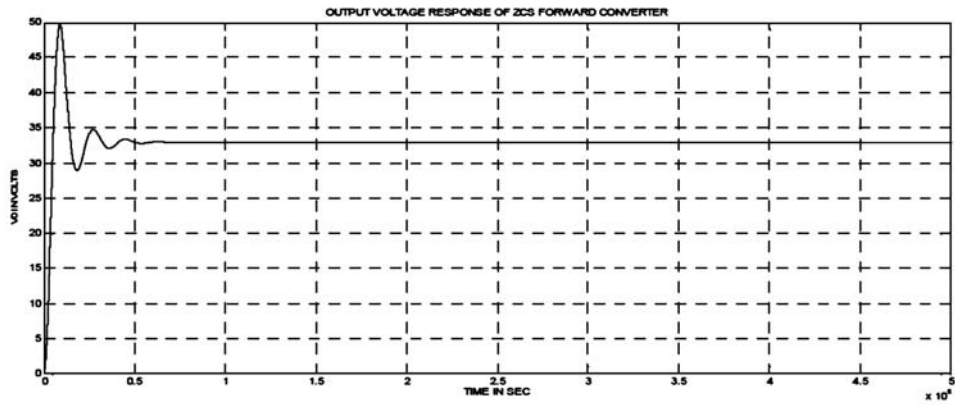


Fig. 17. Output voltage response of ZCS forward converter.

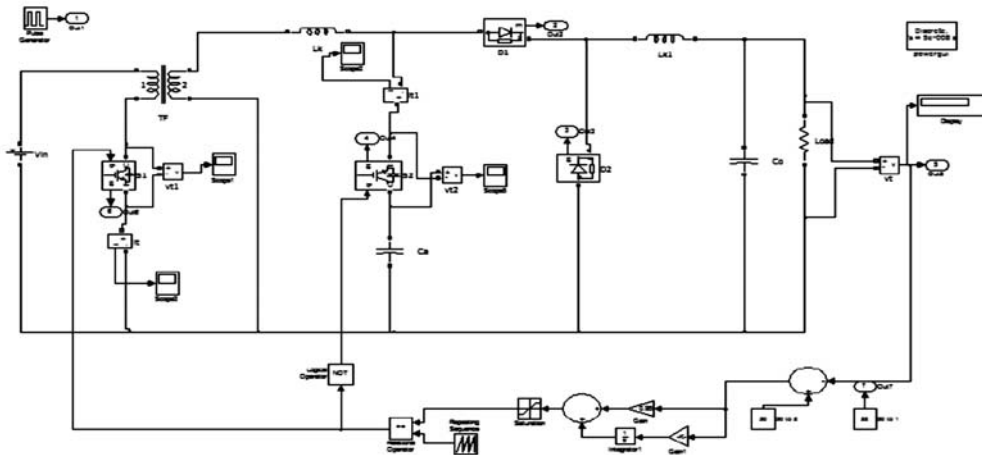


Fig. 18. Simulink model of ZCS forward converter with PI controller.



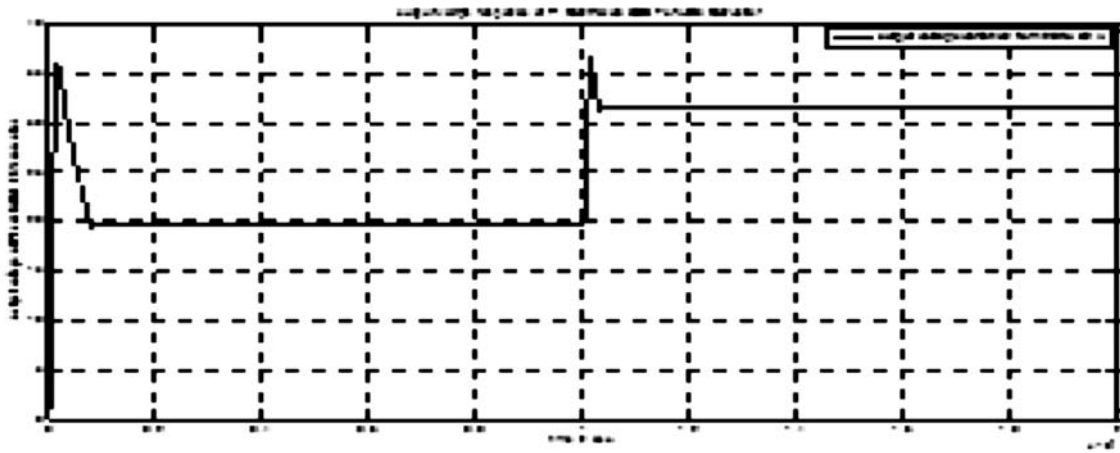


Fig. 19. Output voltage response of zcs forward converter with PI controller.

Fig.19 shows the output voltage step response of PI controlled ZCS forward converter controlled its voltage from 20V to 32V at a step time of  $1\mu$  sec.

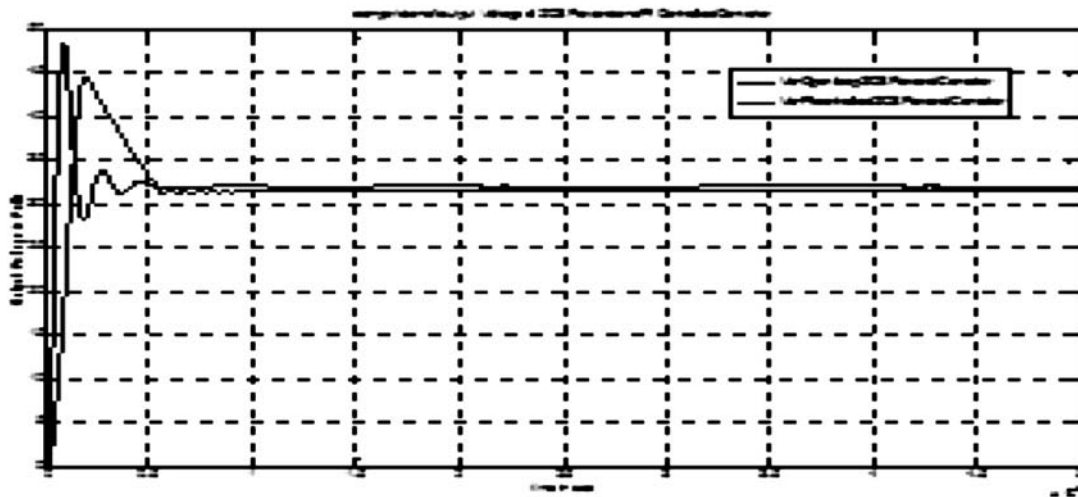


Fig. 20. Comparison of output voltage responses.

## 6. CONCLUSION

In this paper, the Forward converter is soft switched by ZCS technique using simple auxiliary circuit along with closed loop operation using the PI controller. All the devices in this are fully soft switched showing the ZCS operation in section II with a peak current of 10.99 A and 6.925 A of main and auxiliary switch respectively. The simulation analysis shows that the proposed converter doesn't require an additional inductor to reset the transformer core. Also the output voltage is controlled to a desired values by designing the appropriate  $K_p$  and  $K_i$  values of PI controller. In open loop the voltage settles to 32V with more oscillations and with small disturbances at steady state whereas, the voltage in closed loop with controller settles to desire value of 32V with no oscillations as shown in Fig.20.

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